

Cycle-based Programming of Distributed Systems: The Synchrony Hypothesis

Michael Mendler

Faculty of Information Systems and Applied Computer Sciences
University of Bamberg, Germany



Overview

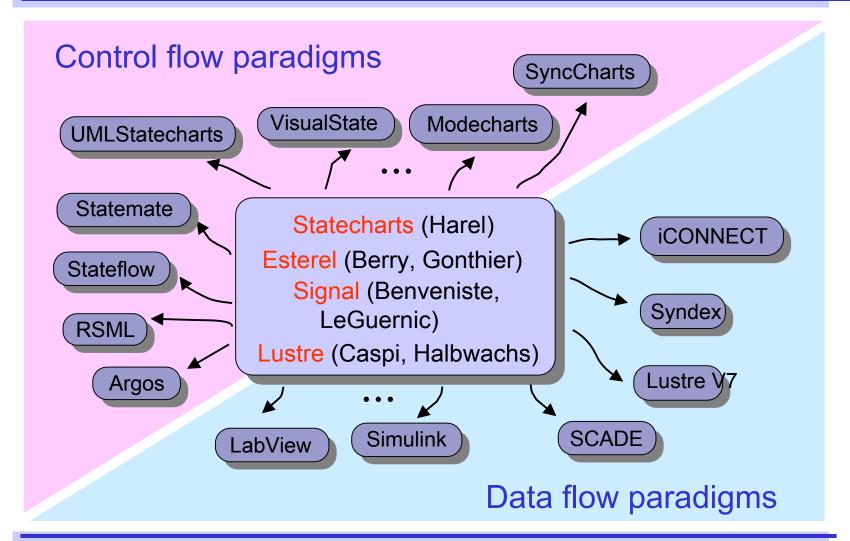
- 1. Synchronous Programming
- 2. The Synchrony Hypothesis
- 3. Causal Reaction = Fixed Point?
- 4. What's in a Step ?: Notions of Causality
- 5. The Synchrony Hypothesis (Hypo-)Thesis



1. Synchronous Programming

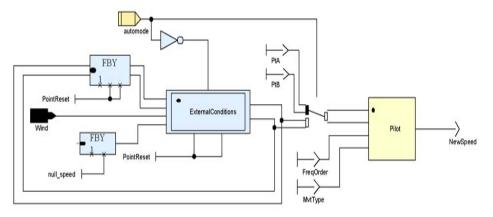


Synchronous Programming

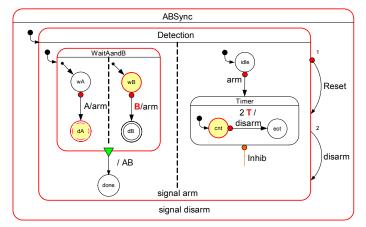




Example: SCADE – Esterel Tech



Data Flow: SCADE Lustre

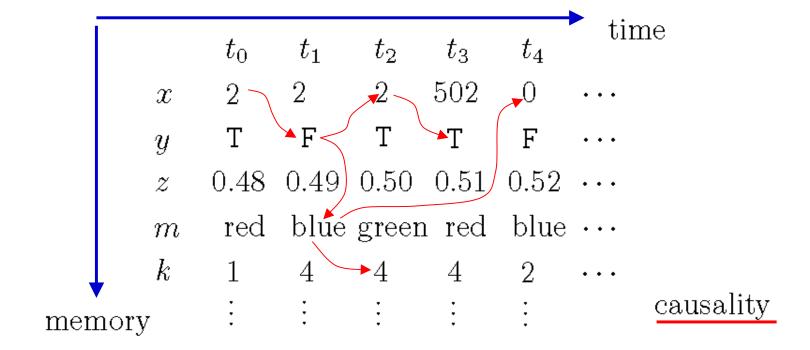


- embedded systems domain (avionics, automotive)
- rigorous semantics
- verification & testing (certification)
- code-generation
- hw/sw codesign

Control Flow: SCADE Safe State Machines

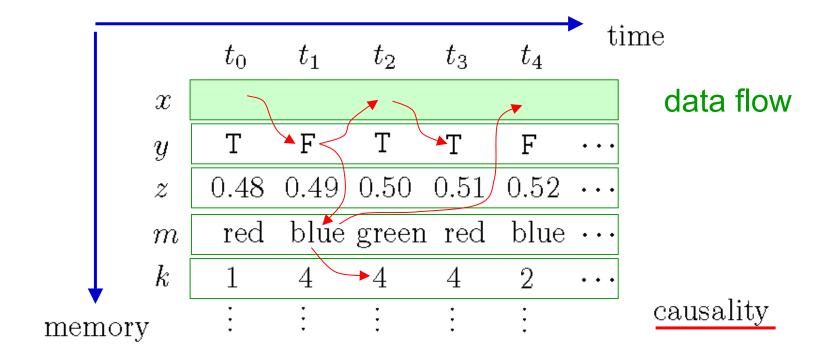


Orthogonality in Time and Space





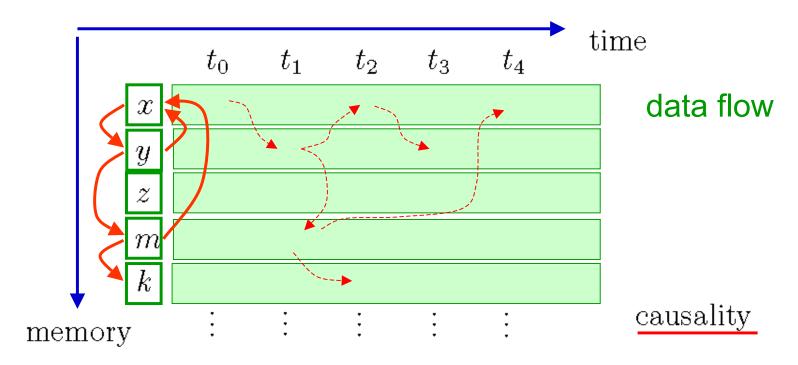
Data Flow





Data Flow

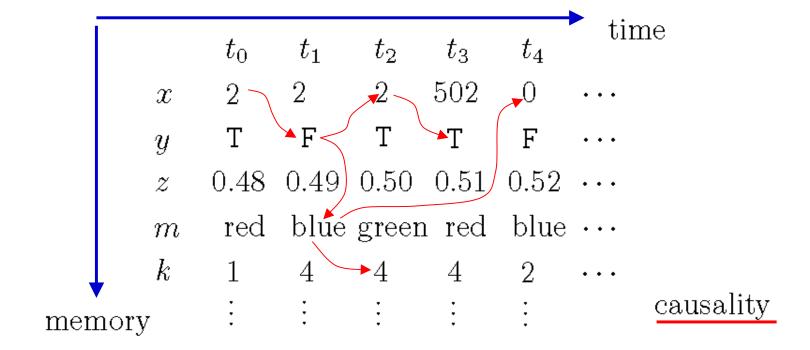
Q: How do we treat the cyclic DF dependencies?



A: Continuitiy Hypothesis, Kahn stream semantics!

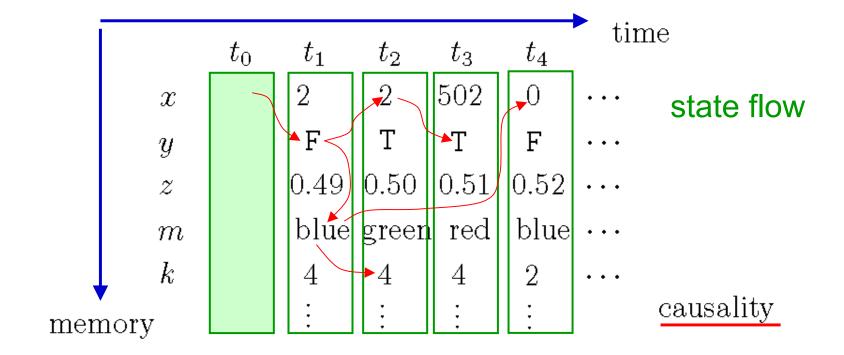


Orthogonality in Time and Space





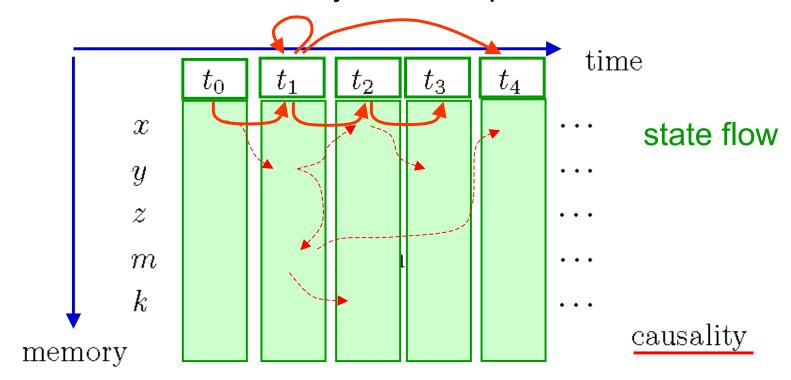
State Flow





State Flow

Q: How do we treat the cyclic SF dependencies?



A: Synchrony Hypothesis, Fourman response semantics



2. The Synchrony Hypothesis



Synchrony Hypothesis

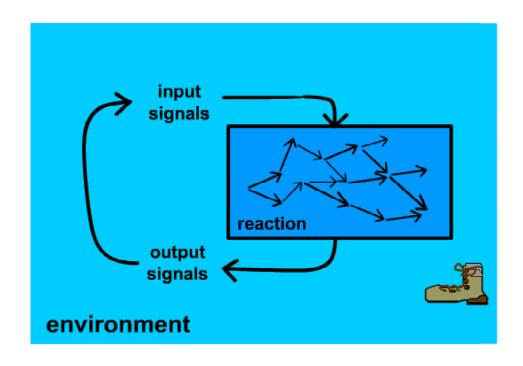
Environment view:

Reactions are

- atomic
- deterministic
- bounded

System view: Reactions may be

- non-atomic
- non-deterministic
- unbounded



"A reactive system is faster than its environment, hence reactions can be considered atomic"



The Synchrony Paradox

Environment view:

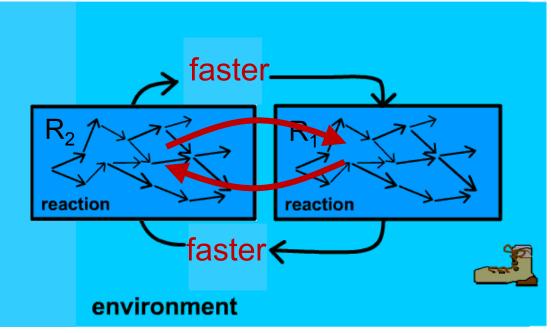
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System view: Reactions may be

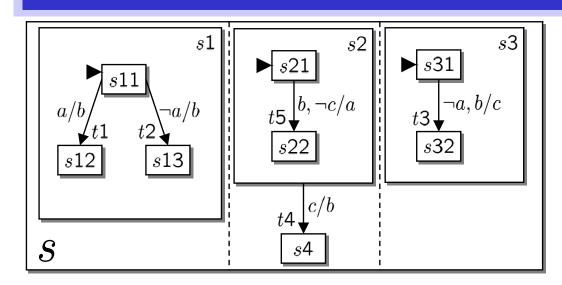
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"A reactive system is faster than its environment, hence reactions can be considered atomic"



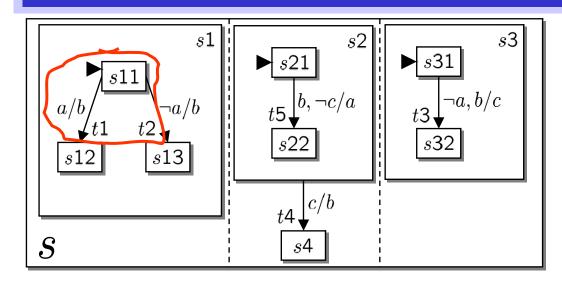
Programming Synchronous Reactions



- logical transitions
- conjunctions = parallelism
- negations code choices, priorities and hierarchy



Programming Synchronous Reactions

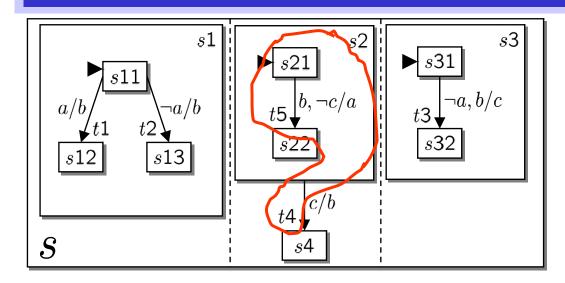


- logical transitions
- conjunctions = parallelism
- negations code choices, priorities and hierarchy

$$REACT := \underbrace{\begin{array}{c} t1 \supset b \land t2 \supset b \land t3 \supset c \land t4 \supset b \land t5 \supset a \land \\ (s11 \land a \land \neg t2) \supset t1 \land \\ (s11 \land \neg a \land \neg t1) \supset t2 \land \\ (s31 \land \neg a \land b) \supset t3 \land \\ (s2 \land c) \supset t4 \land \\ (s21 \land b \land \neg c \land \neg t4) \supset t5 \end{array}}$$



Programming Synchronous Reactions



- logical transitions
- conjunctions = parallelism
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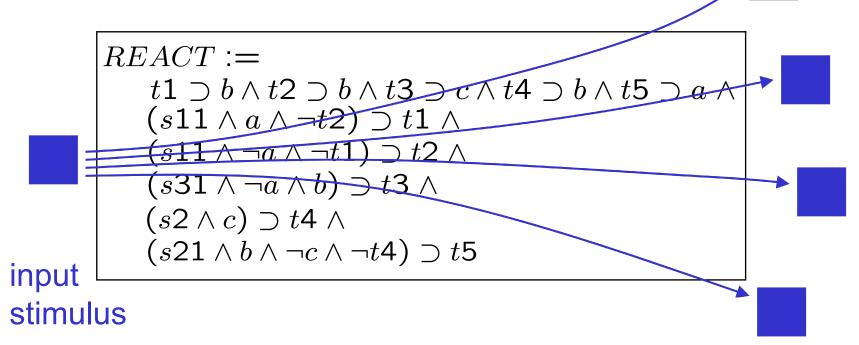
$$REACT := t1 \supset b \land t2 \supset b \land t3 \supset c \land t4 \supset b \land t5 \supset a \land (s11 \land a \land \neg t2) \supset t1 \land (s11 \land \neg a \land \neg t1) \supset t2 \land (s31 \land \neg a \land b) \supset t3 \land (s2 \land c) \supset t4 \land (s21 \land b \land \neg c \land \neg t4) \supset t5$$



Synchronous Abstraction

In which sense does **REACT** describe an atomic macro step?

instantaneous reaction





Synchronous Abstraction

In which sense does **REACT** instantaneous describe an atomic macro step? reaction REACT := $c \wedge t4 \supset b \wedge t5$ $(s2 \land c) \supset t4 \land c$ $(b) \land \neg c \land \neg t4) \supseteq$ $(s21 \land$ input stimulus Cyclic dependencies ? => Fixed-Points!



3. Causal Reaction = Fixed-Point?



Synchronous Reactive Component

Reactive component

$$C = (\mathbb{S}, \mathbb{T}, pos, neg, act)$$

 \mathbb{S}, \mathbb{T} atomic logical signals, logical transitions $pos, neg, act : \mathbb{T} \to 2^{\mathbb{S}}$ positive, negative triggers, actions

Response of C



$$action(T) = \{s \mid \exists t \in T. \ s \in act(t)\}$$

$$T \subseteq \mathbb{T}$$

$$enabled(S) = \{t \mid pos(t) \subseteq S \land neg(t) \subseteq \overline{S}\}$$

$$S \subseteq \mathbb{S}$$

$$AE_C(S) = action(enabled(S))$$
 "response function"



Reaction = Fixed-Point?

Logical Coherence [Berry]

"A signal s is present in an instant if and only if an `emit s' statement is executed in this instant."

-Logical Coherence & Reactiveness

- A response S is logically coherent iff S is a fixed-point of AE_C , i.e., $S = AE_C(S)$.
- C is logically reactive iff it in every activation state and environment, AE_C has a fixed-point.



Causal Response = Unique Fixed Point ?

Problem

The response function

$$AE_C(S) = action(\{t \mid pos(t) \subseteq S \land neg(t) \subseteq \overline{S}\})$$

is not monotonic!



Causal Response = Unique Fixed Point?

Problem

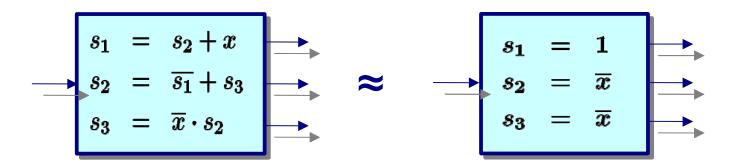
The response function

is not monotonic!

- no unique (least) fixed points!
- compositionality and full-abstraction problems!
- different computation methods!
 - → different notions of steps, instants, reactions ...



Example



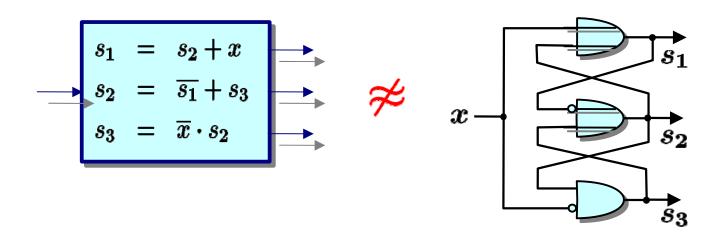
For all inputs there is a unique stationary Boolean fixed point. Thus, the system is logically reactive.

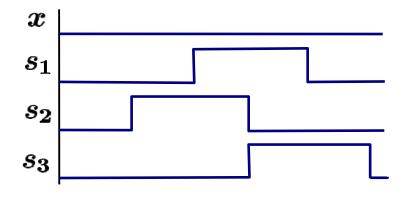
We can compile & execute Boolean solution atomically!

But what if we are compiling for a component-based and distributed architecture?



Example

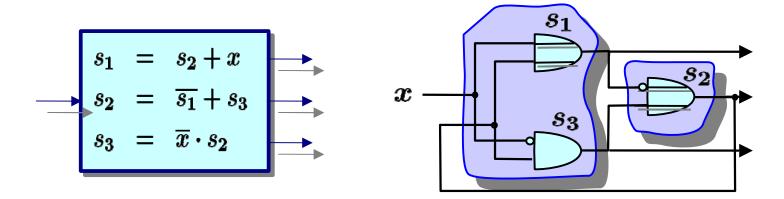




Oscillation under up-bounded inertial delay scheduling [Brzozowski & Seger]



Example



Oscillation can be avoided if we

- schedule s₁, s₃ with higher priority than s₂ or
- implement s₁, s₃ atomically, as a 2in/2out block.

Then, whenever s₂ is executed, we maintain the invariant

$$s_2 = \overline{s_1} + s_3 = \overline{x}$$



4. What is in a Step? Notions of Causality



1 Avoid Negations

only positive triggers [Modecharts '94, Argos '89]

2 Modify Semantics of Negation

- give up global consistency [Huizing&al.'88, Modecharts'96]
- add consistency as implicit trigger
 [Maggiolo-Schettini &al. '96, Lüttgen &al. '99]

3 Give up Synchrony Hypothesis (no abstraction)

- all signals delayed[Statemate 90, VHDL, RSML 95, PretC 09]
- negative triggers delayed [Saraswat TCCP'94, Boussinot & deSimone SL'95, Boussinot FunLoft'07]



4 Conflict-avoiding Schedules

- only accept stratifiable (statically schedulable) programs
 [Normal Logic Programming]
- sequential schedule (endochrony) [Benveniste &al. '00]
- NRSA "no reaction to signal absence" (weak endochrony, concurrent input reading) [Butucaru, Caillaud '06]



5 Self-scheduled Run-time (explicit absence, dual rail)

non-deterministic speculation on absence
 [Pnueli & Shalev '91; Boussinot's "basic semantics" '98]



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"Feel free to assume the absence of a signal as long as it is consistent to do so; if necessary, backtrack!"

- fully-abstract, compositional intuitionistic Kripke semantics [Lüttgen & Mendler '01]
- game-theoretic "lazy" fixed-points [Aguado & Mendler '05]



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- constructiveness = "computed" absence [Berry '00]



5 Self-scheduled Run-time (explicit absence, dual rail)

- non-deterministic speculation on absence
 [Pnueli & Shalev '91; Boussinot's "basic semantics" '98]
- constructiveness = "computed" absence [Berry '00]
 - "Accept the absence of a signal only under computable evidence that it may not occur later"
 - game-theoretic "eager" fixed-points [Aguado & Mendler '05]
 - delay-insensitivity = non-inertial delay= constructive modal logic [Mendler & Shiple & Berry '07]
 - SugarCubes [Boussinot '98] (Esterel v3,v4,v5,v6,v7)
- & many other hardware approaches
 - speed-independence, semi-modularity, distributivity, ...



5. The Synchrony Hypothesis Thesis



Outlook

Thesis 1

There are as many notions of constructive causality as there are scheduling/run-time models

Thesis 2

Synchronous reaction requires intensional semantics:

classical Boolean logic

⇒ constructive logic (e.g., Heyting algebra)

least and greatest fixed points

⇒ general game-theoretic fixed points



Thank You!